Shapley Value based Variable Interaction Networks for Data Stream Analysis

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Jan Zenisek, Sebastian Dorl, Stephan Winkler and Michael Affenzeller

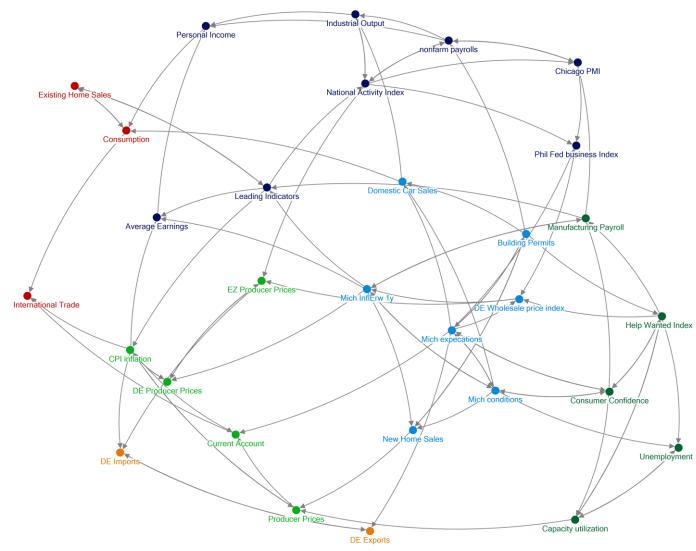


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Part I – Method Variable Interaction Network (VIN)



= directed, weighted graph

Nodes: variables

Edges: impact of variables on others

[1] Kronberger et al. Genetic Programming: Current Trends and Applications in Computational Finance, Nova Science Publishers, 2013

[2] Hooker, Giles. *Discovering additive structure in black box functions.* Proceedings of the tenth ACM SIGKDD international conference on Knowledge discovery and data mining, 2004.

Part I – Method Variable Interaction Network: Modeling

1. Alternate targets & inputs

target	input variables				
x1	x2	x3	x4	x 5	
1.1	1.4	1.7	1.3	1.2	
1.2	1.3	1.4	1.5	1.3	
1.2	1.1	1.4	1.9	1.4	
1.4	0.9	1.2	1.3	1.4	
1.2	1.2	1.6	1.2	1.7	

x2

2. Calculate variable impacts

For all models do: For all inputs do:

2.1 Remove variable info, e.g. shuffle values

2.2 Recalculate model error, e.g. R^2 \rightarrow Error increase = impact

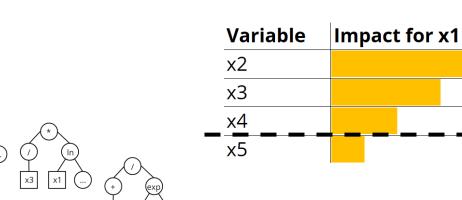
Example calculation for model target=x1:

0.252

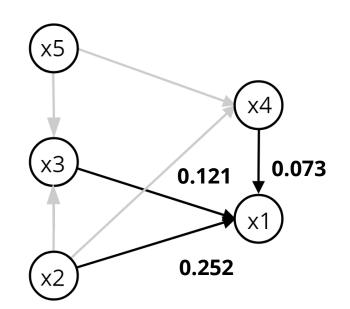
0.121

0.073

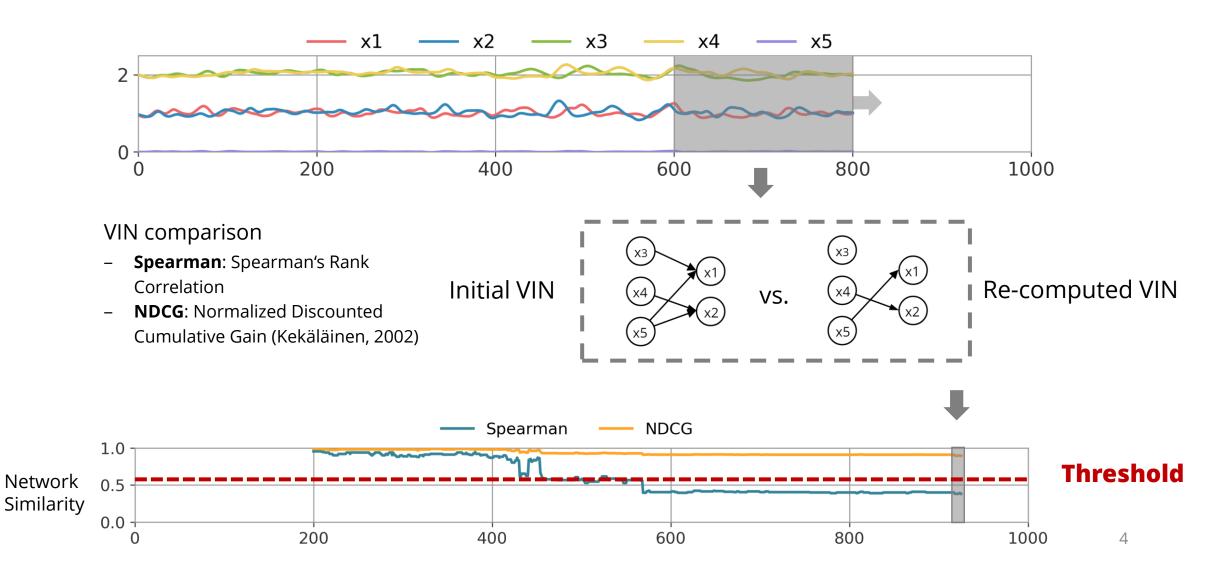
0.037



3. Create network



Part I – Method Variable Interaction Network: Evaluation



Part I – Method Variable Interaction Network

Model Type Characteristics

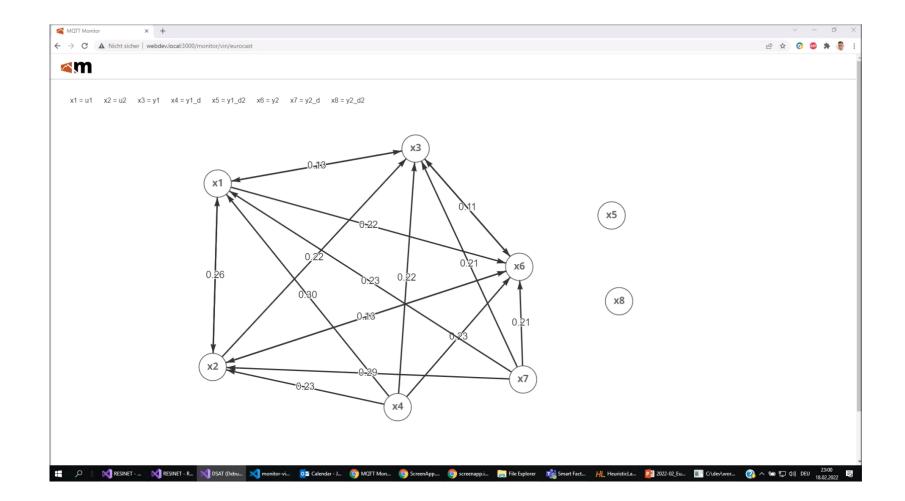
Enables holistic system analysis ...also on streaming data [3]
 Agnostic to the regression algorithms / models used as base
 Fast to create, once regression models are built

✓ Infeasible for high-dimensional data without pruning

✓ Non-deterministic modeling & evaluating causes network alternatives

[3] Zenisek, J., Kronberger, G., Wolfartsberger, J., Wild, N., & Affenzeller, M. Concept Drift Detection with Variable Interaction Networks. In International Conference on Computer Aided Systems Theory (pp. 296-303). Springer, Cham, 2020.

Part I – Method VIN Evaluation Instability (Video)



Part I – Method VI Network: Modeling (cont.d)

1. Alternate targets & inputs

target	input variables				
x1	x2	x3	x4	x5	
1.1	1.4	1.7	1.3	1.2	
1.2	1.3	1.4	1.5	1.3	
1.2	1.1	1.4	1.9	1.4	
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1.2	1.2	1.6	1.2	1.7	

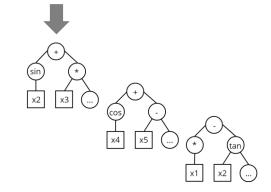
2. Calculate variable impacts 3. C

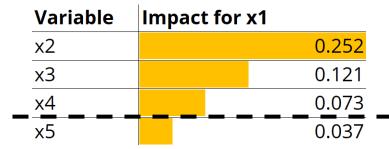
For all models do: For all inputs do:

2.1 Remove variable info, e.g. shuffle records

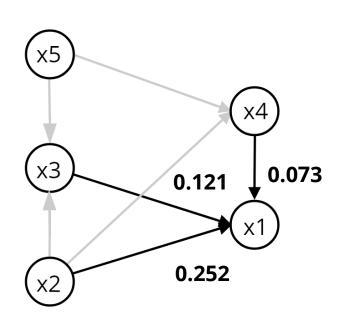
2.2 Recalculate model error, e.g. R² → Error increase = impact

= Permutation Feature Importance [3] Example calculation for model target=x1:





3. Create network



Part I – Method Shapley Value based Variable Impact [5]

Feature contribution to the difference between the actual prediction and the mean prediction

- 1. Create all possible feature coalitions with and without the targeted feature
- 2. Calculate "actual prediction mean prediction" difference for each coalition
- 3. Average differences between coalitions with and without the targeted feature
- Coalition game theory (solid mathematical foundation)
- Local and model agnostic
- Computationally expensive

Customization:

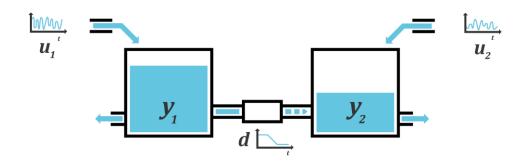
- Use of nmse and impact threshold
- Average absolute shapley value of current set (global analysis)
- Normalize outcome

Part II - Experiments Benchmarking Problems for VINs

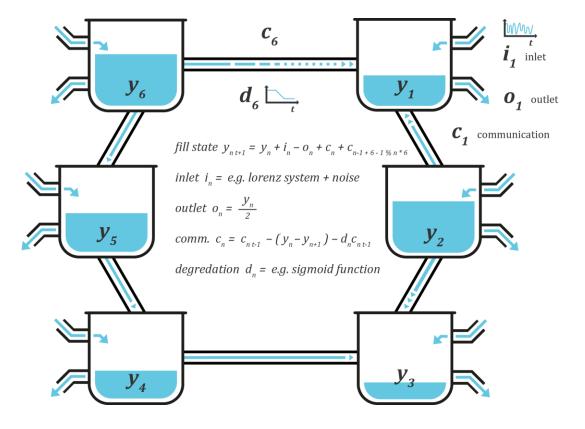
Communicating Vessels

Circular Connected CVs (new)

- Inherently stable
- *d* = introduced drift (hidden) to simulate gradually clogging communication path



[3] Zenisek, J., Kronberger, G., Wolfartsberger, J., Wild, N., & Affenzeller, M. Concept Drift Detection with Variable Interaction Networks. In International Conference on Computer Aided Systems Theory (pp. 296-303). Springer, Cham, 2020.

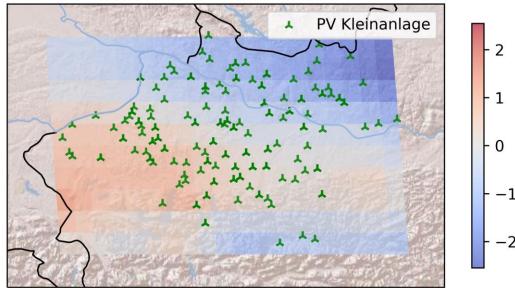


Part II - Experiments Real World Problem: Photovoltaic Power Production

Available Data:

- 190 privately owned photovoltaic systems
- including battery packs
- Recordings from 2014 to 2019
- Recording interval: 5 min, ~100 Mio. data rows
- Constant parameters: geolocation, manufacturer, capacity,...
- Measured features: PV production, power consumption, grid input/output, battery charge, discharge, SOC

ERA5_Land - Upper Austria 23:30 31st of Dec 2015



Main goals:

- Prediction models for power production & consumption
- Network resilience analysis

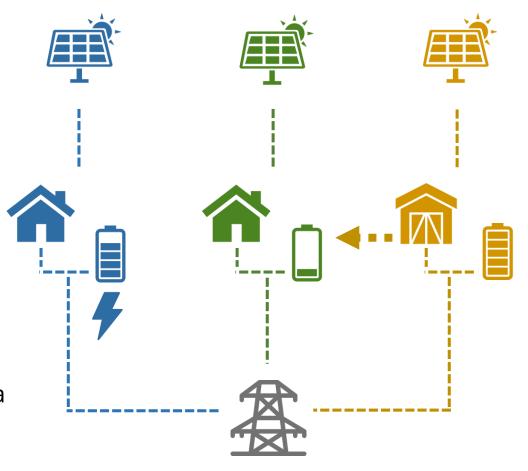
Part II - Experiments Network Resilience Simulations (Resinet)

What happens if...

- ... weather is sunny (everywhere)?
- ... weather is bad (for a long period)?
- ... n% of the batteries have an outage?
- ... batteries degrade faster than expected?
- ... batteries are connected (shared memory)?

How do we detect/predict system drifts? → Sliding window based VIN-comparison

Motivation for VINs: Structure knowledge Motivation for Shapley Values: Forecasted data



Part II - Experiments Network Resilience Simulations (Resinet)

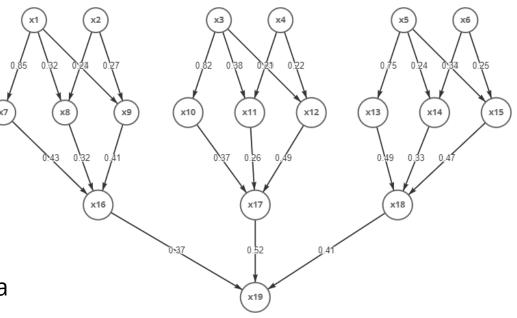
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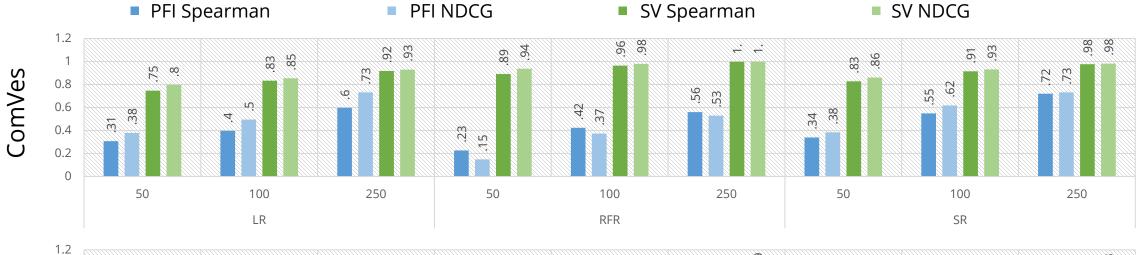
How do we detect/predict system drifts? → Sliding window based VIN-comparison

Motivation for VINs: Structure knowledge Motivation for Shapley Values: Forecasted data

x1 = weather1 x2 = system1 x3 = weather2 x4 = system2 x5 = weather3 x6 = system3 x7 = pvProduction1 x8 = powerConsumption1 x9 = batterySOC1 x10 = pvProduction2 x11 = powerConsumption2 x12 = batterySOC2 x13 = pvProduction3 x14 = powerConsumption3 x15 = batterySOC3 x16 = gridDiff1 x17 = gridDiff2 x18 = gridDiff3 x19 = gridDiff

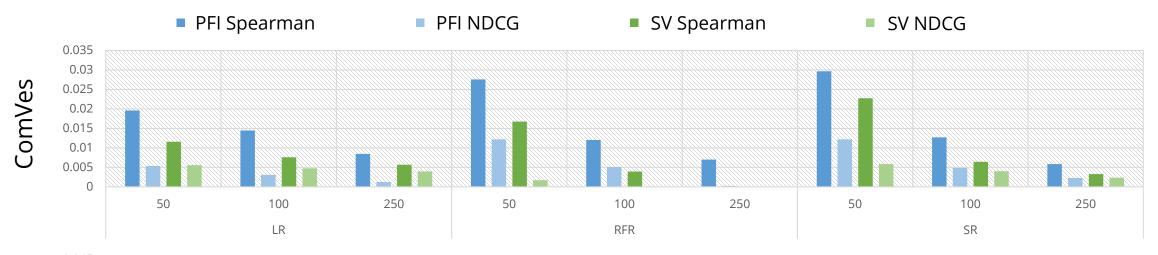


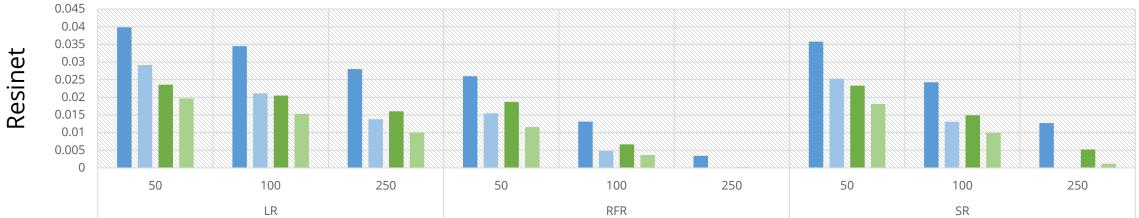
Part II - Experiments Stability Test Results: Stability Ratio





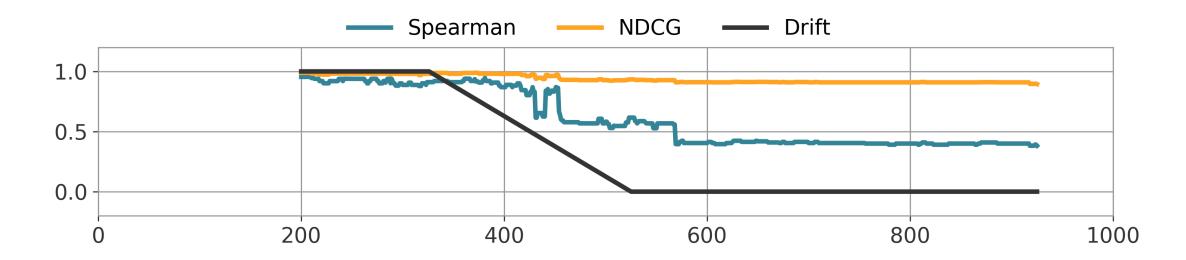
Part II - Experiments Stability Test Results: SD of Changes





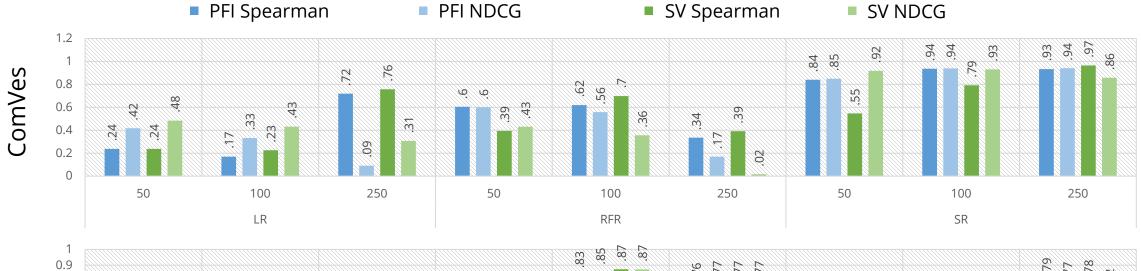
Part II - Experiments Introducing Drift

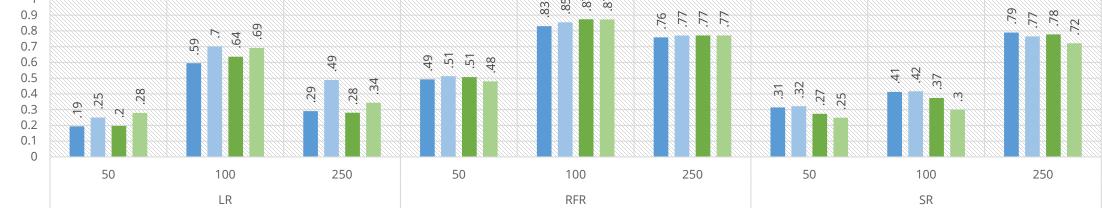
Communicating Vessels: clogging communication paths **Photovoltaic Network:** shared batteries + individual outages **Detection scoring:** *Pearson R* of (hidden) drift and network similarity



Part II - Experiments Drift Test Results: Pearson R

Resinet





Part II - Experiments Implementation and "Root-Cause" Analysis

m

 $x1 = age1 \quad x2 = age2 \quad x3 = age3 \quad x4 = batterySOCWh1 \quad x5 = batterySOCWh2 \quad x6 = batterySOCWh3 \quad x7 = dayLength1 \quad x8 = dayLength2 \quad x9 = dayLength3 \quad x10 = globalRadiation1 \quad x11 = globalRadiation2 \quad x12 = globalRadiation3 \quad x13 = globalRadiationSum2h1 \quad x14 = globalRadiationSum2h2 \quad x15 = globalRadiationSum2h3 \quad x16 = globalRadiationSumFrame07to12h1 \quad x17 = globalRadiationSumFrame07to12h2 \quad x18 = globalRadiationSumFrame07to12h3 \quad x19 = gridDiff \quad x20 = gridDiff1 \quad x21 = gridDiff2 \quad x22 = gridDiff3 \quad x23 = hoursAfterSunrise1 \quad x24 = hoursAfterSunrise2 \quad x25 = hoursAfterSunrise3 \quad x26 = powerConsumption1 \quad x27 = powerConsumption2 \quad x31 = pvProduction2 \quad x31 = pvProduction3$

dayLength1 x25 (x1 х8 х9 x10 x11 x12 x13 x14 x15 x16 x17 x18 x23 x24 0.31 (0:0248 (0.38) 0.2118 0.31 0.28 (0.27) 0.35 0.38 (0.36) 0.50 4447) - - 0.40 - - -0.76 (0.53)2 (0.0.92 (0.82) 0.37-0.17-(0.41) 0.24 (0.35) powerConsumption1 x27 x28 x29 x30 x31 x26 0.11 (0.0714 (0.0714 (0.0615 (0.10))8 (0.0614 (0.0749 (0.30))0 (0.0947 (0.32) 0.14 (0.25) "Hotpath" Heuristic gridDiff1 x20 x21 x22 1. De-cycle graph: iteratively remove weakest link on 0.43 (0.:0331 (0.:0126 (0.21) next shortest cycle 2. Generate all paths from source to target nodes (DFS) gridDiff 3. Highlight path with highest change sum

Take-Home Messages and Outlook

Variable Interaction Networks (VIN)

- enable holistic system analysis (also on streaming data)
- enable knowledge integration (i.e. network structure)
- currently underrepresented in the field Explainable / Interpretable AI

	Evaluation	Precision	Stability	Data Access
– based on PFI:	fast	high	mediocre	input, true outcome
– based on SV:	slow (bulk), fast (streaming)	high	high	input

Further leads: extend root-cause analysis

- "Hotpath" improvement, e.g. add memory (find most stable over time)
- Classification approach

Q & A Shapley Value based Variable Interaction Networks for Data Stream Analysis

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[4] Breiman, L.: Random forests. Machine learning 45(1), 5–32 (2001)

[5] Shapley, Lloyd S. "A value for n-person games." Contributions to the Theory of Games 2.28 (1953): 307-317

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